Industrial Grade -203 Series DiskOnModule (DOM) Product Manual

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1. Introduction to Cactus Technologies® -203 Series Industrial Grade DOM Products

Features:

- Solid state design with no moving parts
- Plugs into industry standard IDE 40/44 pin sockets
- Supports ATA PIO Modes 0-4
- Supports DMA Modes 0-2
- High reliability, MTBF > 4,000,000 hrs.
- Enhanced error correction, < 1 error in 10^{14} bits read
- Intelligent power management to reduce power consumption
- Dual voltage support: 3.3V/5.0V

Overview:

Cactus Technologies® DiskOnModule (DOM) is a low capacity solid-state flash memory product that complies with the ANSI ATA standard and is electrically compatible with an IDE disk drive. Cactus Technologies® DOMs provide up to 1GB of formatted storage capacity and is designed to plug in directly to IDE connectors on an industrial PC motherboard. Cactus Technologies® DOMs are designed to be used in applications which requires a low capacity solid state disk that is IDE compatible.

Cactus Technologies® Industrial Grade DOM products use high quality flash memory from well known vendors, such as Toshiba Corporation. In addition, it includes an on-drive intelligent controller that manages interface protocols, data storage and retrieval as well as ECC, defect handling and diagnostics, power management, and clock control.

1.1. Supported Standards

Cactus Technologies® DOM is fully electrically compatible with the following specification:

- ATA 5 Specification published by ANSI: X3.221 AT Attachment Interface for Disk Drives

1.2. Product Features

Cactus Technologies® Industrial DOM contains a high level, intelligent controller. This intelligent controller provides many capabilities including the following:

- Standard ATA register and command set (same as found on most magnetic disk drives).
- Management of erasing and programming the flash memory independent of the host system
- Sophisticated defect managing capabilities (similar to magnetic disk drives).
- Sophisticated system for error recovery using powerful error correction code (ECC).
- Intelligent power management for low power operation.

1.2.1. Host and Technology Independence

Cactus Technologies® Industrial DOM appears as a standard ATA disk drive to the host system. The drive utilizes a 512-byte sector which is the same as that in an IDE magnetic disk drive. To write or read a sector (or multiple sectors), the host computer software simply issues an ATA Read or Write command to the drive as per the ATA protocol. The host software then waits for the command to complete. The host system does not get involved in the details of how the flash memory is erased, programmed or read as this is all managed by the built-in controller in the drive. Also, with the intelligent on-board controller, the host system software will not require changing as new flash memory evolves. Thus, systems that support the Cactus Technologies® Industrial DOM products today will continue to work with future Cactus Technologies® Industrial DOMs built with new flash technology without having to update or change host software.

1.2.2. Defect and Error Management

Cactus Technologies® Industrial DOM contains a sophisticated defect and error management system similar to those found in magnetic disk drives. The defect management is completely transparent to the host and does not consume any user data space.

The soft error rate for Cactus Technologies® Industrial DOMs is much lower than that of magnetic disk drives. In the extremely rare case where a read error does occur, the drive has sophisticated ECC to recover the data.

These defect and error management systems, coupled with the solid-state construction, give Cactus Technologies® Industrial DOMs unparalleled reliability.

1.2.3. Intelligent Power Management

Cactus Technologies® Industrial DOM employs sophisticated power management algorithms to conserve power. Upon completion of a command, the drive will automatically enter sleep mode if no further commands are received. In most situations, the drive will be in sleep mode except when the host is accessing it, thus conserving power.

When the drive is in sleep mode, any command issued to the drive will cause it to exit sleep and respond.

1.2.4. Power Supply Requirements

Cactus Technologies® Industrial DOM is a dual voltage product, which means it will operate at a voltage range of 3.30 volts ±10% or 5.00 volts ± 10%.

2. Product Specifications

For all the following specifications, values are defined at ambient temperature and nominal supply voltage unless otherwise stated.

2.1. System Environmental Specifications

Table 2-1. Environmental Specifications

		Cactus Technologies® DOM
Temperature	Operating:	0° C to +70° C (Standard) -45° C to +90° C (Extended)
Humidity	Operating & Non-Operating:	8% to 95%, non-condensing
Acoustic Noise		0 dB
Vibration	Operating & Non-Operating:	15 G peak to peak maximum
Shock	Operating & Non-Operating:	50G max. operating; 1,000 G max. non-operating
Altitude (relative to sea level)	Operating & Non-Operating:	70,000 feet maximum

2.2. System Power Requirements

Table 2-2. Power Requirements

		Cactus Technologies® DOM	
DC Input Voltage (VCC) 100 mV max. ripple (p-p)		3.3V ±10%	5V ±10%
(Maximum Average Value) See Notes.	Sleep: Reading: Writing:	400 µA 45 mA 53 mA	800 µA 47 mA 58 mA

NOTES: All values quoted are worst case at low temperature and high supply voltage unless otherwise stated.

Sleep mode is specified under the condition that all drive inputs are static CMOS levels and in a “Not Busy“ operating state.

2.3. System Performance

All performance timings are typical values under normal operating conditions and assuming the drive controller is in the default (i.e., fastest) mode.

Table 2-3. Performance

Start Up Times	Reset to ready:	35 msec typical
Read Transfer Rate		8.0 MBytes/sec
Write Transfer Rate		6.0 MBytes/sec

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2.4. System Reliability

Table 2-4. Reliability

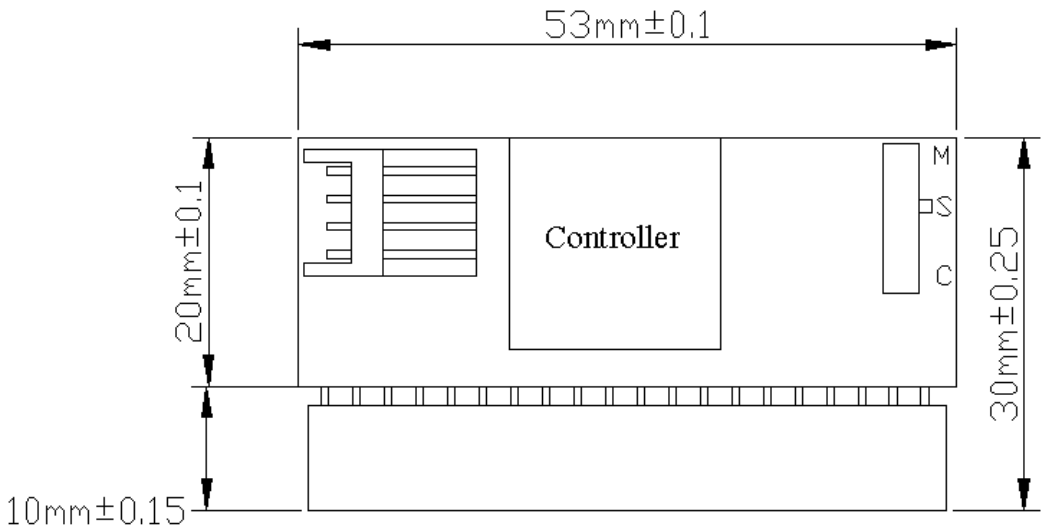
MTBF (@ 25°C)	> 4,000,000 hours
Data Reliability	< 1 non-recoverable error in 10^{14} bits READ
Endurance:	> 2,000,000 erase/program cycles

2.5. Physical Specifications

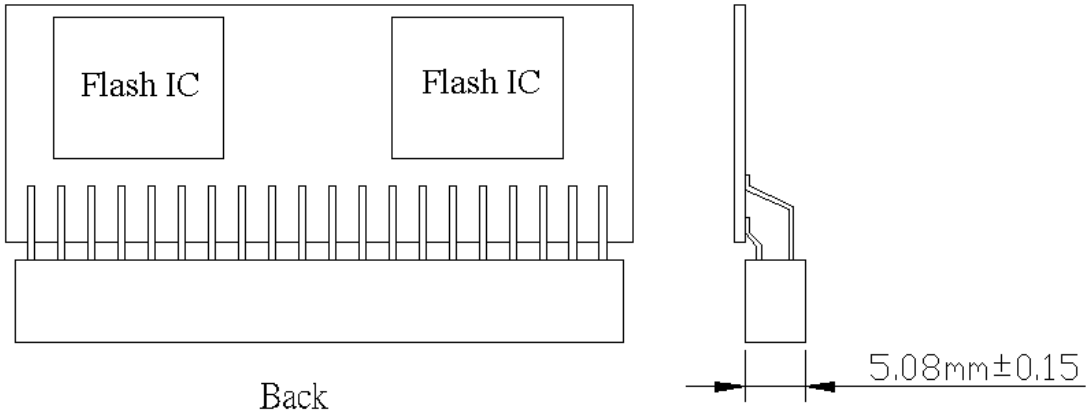
The following sections provide the physical specifications for Cactus Technologies® Industrial DOM products.

2.5.1. DOM Physical Specifications

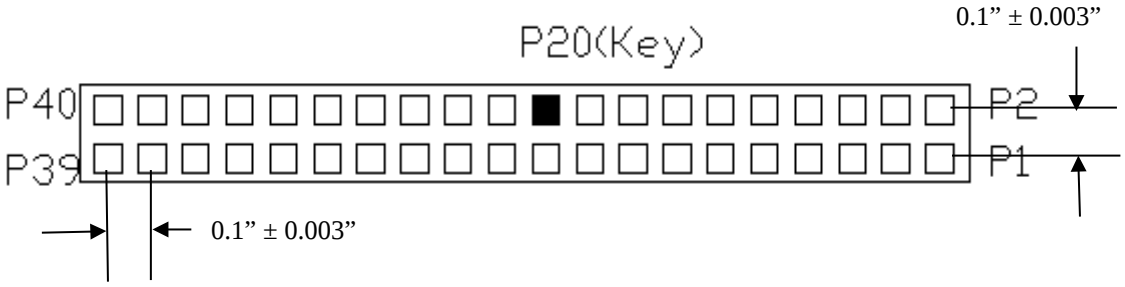
Refer to Figure 2-1 for Cactus Technologies® 40-pin DOM physical specifications and dimensions and Figure 2-2 for Cactus 44-pin DOM physical specifications.


53mm±0.1
20mm±0.1
Controller
M
S
C
30mm±0.25
10mm±0.15

Front


Flash IC
Flash IC
5.08mm±0.15

Back


0.1" ± 0.003"
P20(Key)
P40
P39
P2
P1
0.1" ± 0.003"

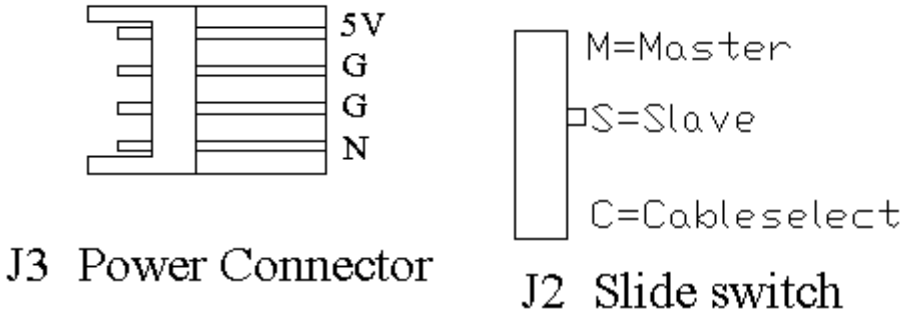
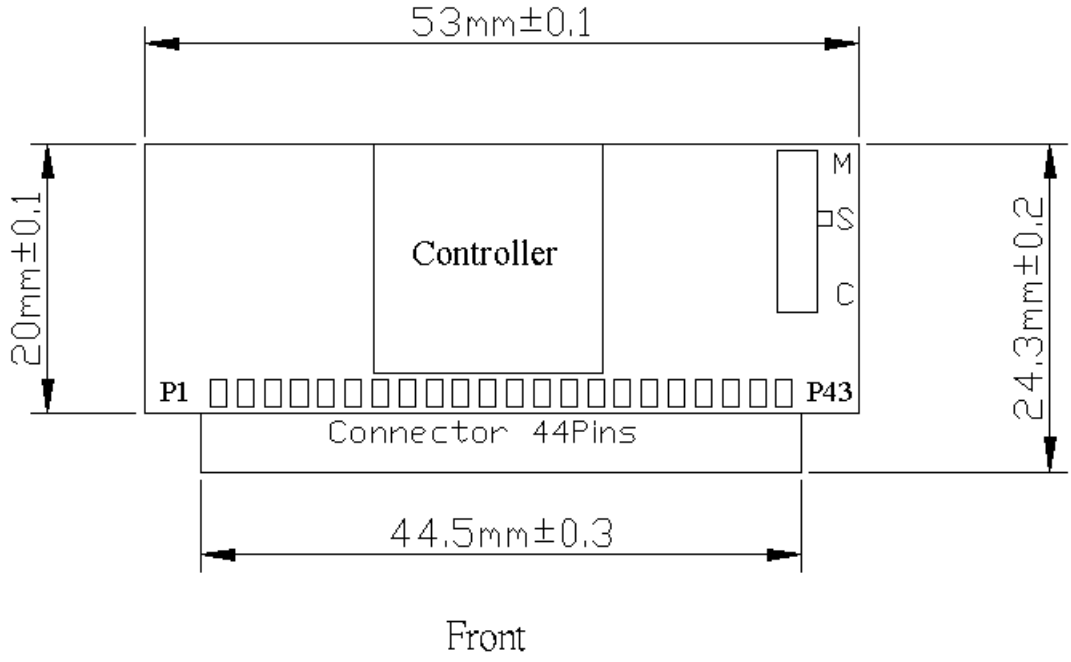
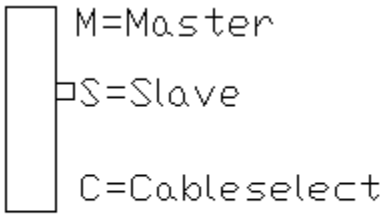


Figure 2-1. 40-pin DOM physical specifications





J2 Slide switch

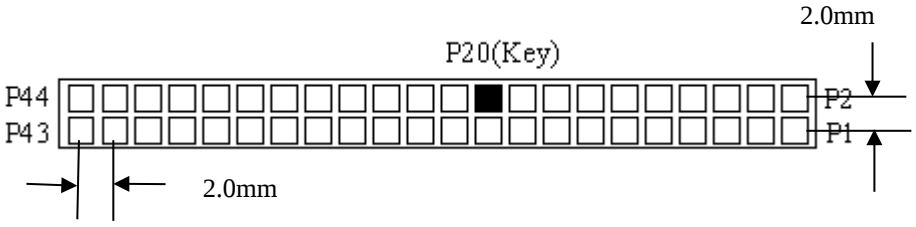


Figure 2-2 44-pin DOM physical specifications

2.6. Capacity Specifications

The following sections provide capacity specifications for Cactus Technologies® DOM products.

2.6.1. DOM Capacity Specifications

Cactus Technologies DOM is available in capacities of 128MB, 256MB, 512MB and 1GB.

3. Interface Description

The following sections provide detailed information on the Cactus Technologies® Industrial DOM interface.

3.1. DOM Pin Assignments and Pin Type

The signal/pin assignments are listed in Table 3 -5. Low active signals have a “-” prefix. Pin types are Input, Output or Input/Output. Sections 3.3.1 to 3.3.4 define the DC characteristics for all input and output type structures.

Table 3-5. 40/44 DOM Pin Assignments and Pin Type

Pin #	Signal Name	Pin Type	Pin #	Signal Name	Pin Type
1	-Reset	I	2	GND	
3	Data 7	I/O	4	Data 8	I/O
5	Data 6	I/O	6	Data 9	I/O
7	Data 5	I/O	8	Data 10	I/O
9	Data 4	I/O	10	Data 11	I/O
11	Data 3	I/O	12	Data 12	I/O
13	Data 2	I/O	14	Data 13	I/O
15	Data 1	I/O	16	Data 14	I/O
17	Data 0	I/O	18	Data 15	I/O
19	GND		20	Key	
21	-DMARQ	O	22	GND	
23	-IOW	I	24	GND	
25	-IOR	I	26	GND	
27	Reserved		28	-CSEL	I
29	-DMACK	I	30	GND	
31	IRQ	O	32	-IOCS16	O
33	A1	I	34	-PDIAG	I/O
35	A0	I	36	A2	I
37	-CS0	I	38	-CS1	I
39	-DASP	I/O	40	GND	
41	Vcc		42	Vcc	
43	GND		44	Reserved	

Note: Pins 41-44 available on 44pin DOMs only

3.2. Signal Description

Table 3 -6 describes the I/O signals. Signals whose source is the host are designated as inputs while signals that the DOM sources are outputs. The DOM logic levels conform to those specified in the *ANSI ATA Specification*.

Table 3-6. Signal Description

Signal Name	Dir.	Description
A2—A0	I	A[2:0] is used to select the one of eight registers in the Task File.
-PDIAG	I/O	This input/output is the Pass Diagnostic signal in the Master/Slave handshake protocol.
-DASP	I/O	This input/output is the Disk Active/Slave Present signal in the Master/Slave handshake protocol.
-CS0, -CS1	I	-CS0 is the chip select for the task file registers while -CS1 is used to select the Alternate Status Register and the Device Control Register.
-CSEL	I	This internally pulled up signal is used to configure this device as a Master or a Slave. When this pin is grounded, this device is configured as a Master. When the pin is open, this device is configured as a Slave.
D15—D00	I/O	These lines carry the Data, Commands and Status information between the host and the controller. D00 is the LSB of the Even Byte of the Word. D08 is the LSB of the Odd Byte of the Word. All Task File operations occur in byte mode on the low order bus D00-D07 while all data transfers are 16 bits using D00-D15.
GND	--	Ground.
-IORD	I	This is an I/O Read strobe generated by the host. This signal gates I/O data onto the bus from the DOM.
-IOWR	I	The I/O Write strobe pulse is used to clock I/O data on the Data bus into the DOM. The clocking will occur on the negative to positive edge of the signal (trailing edge).
INTRQ	O	This signal is the active high Interrupt Request to the host.
-RESET	I	This input pin is the active low hardware reset from the host.
VCC	--	+5 V, +3.3 V power.
-IORDY	O	The -**IORDY** signal is driven by the FlashDrive to extend the I/O cycle in progress.
-IOCS16	O	This output signal is asserted low when this device is expecting a word data transfer cycle.
DMARQ	O	This signal is driven by the DOM to request DMA data transfer to/from the host.
DMACK-	I	This signal is driven by the host in response to a DMA request by the DOM.

3.3. Electrical Specification

The following table defines all D.C. Characteristics for the DOM Series. Unless otherwise stated, conditions are:

Vcc = 5V ± 10% or Vcc = 3.3V ± 10%
Ta = -40°C to 90°C

3.3.1. Absolute Maximum Ratings

Parameter	Symbol	MIN	MAX	Units
Storage Temperature	Ts	-65	+150	°C
Operating Temperature	T_A	-45	+90	°C
Vcc with respect to GND	Vcc	-0.3	6.5	V

3.3.2. DC Characteristics

Parameter	Symbol	MIN	MAX	Units
Input Voltage	Vin	-0.5	Vcc + 0.5	V
Output Voltage	Vout	-0.3	Vcc + 0.3	V
Input Leakage Current	I_{LI}	-10	10	uA
Output Leakage Current	I_{LO}	-10	10	uA
Input/Output Capacitance	C_I/C_o		10	pF
Operating Current Sleep Mode @20 MHz (3.3V) @40 MHz (3.3V) @20 MHz (5.0V) @40 MHz (5.0V)	I_{CC}		 0.8 24 47 30 58	mA

3.3.3. AC Characteristics

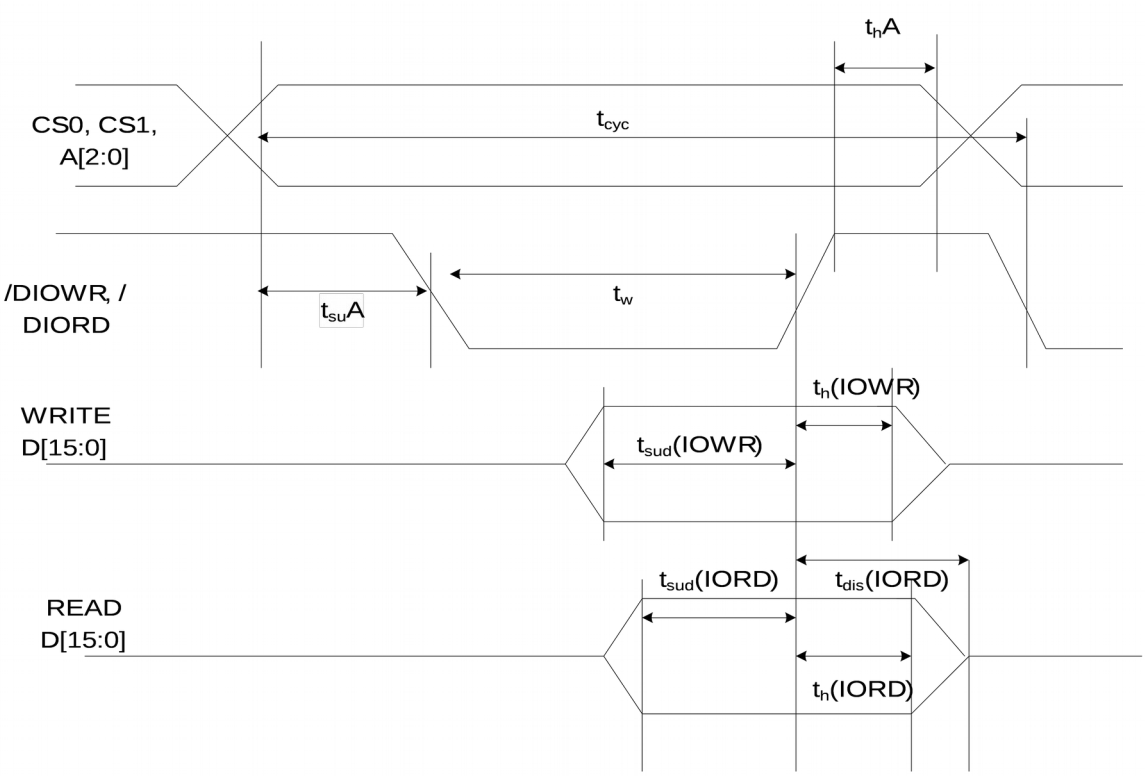
3.3.3.1. Deskewing

The host shall provide cable deskewing for all signals originating from the device. The device shall provide cable deskewing for all signals originating at the host.

All timing values and diagrams are shown and measured at the connector of the selected device.

PIO Transfer Timing defines the relationships between the interface signals for register transfers.

For PIO modes 3 and above, the minimum value of t_cR is specified by word 68 in the IDENTIFY DEVICE parameter list.



1. Device address consists of signals **-CS0**, **-CS1** and **-DA(2:0)**.
2. Data consists of DD(7:0).

Figure 3-3. Register Transfer To/From Device

PIO Timing Parameters		Mode 4 ns	Note
t_{cyc}	Cycle time (min)	120	1

$t_{su}A$	Address valid to IORD-/IOWR- setup (min)	25	
t_w	IORD-/IOWR- pulse width (min)	70	1
t_hA	IORD-/IOWR- recovery time (min)	25	1
t_{su}(IOWR)	IOWR- data setup (min)	20	
t_hD	IOWR- data hold (min)	10	
t_{su}(IORD)	IORD- data setup (max)	20	
t_h(IORD)	IORD- data hold (min)	5	
t_{dis}(IORD)	IORD- data tri-state (max)	30	2
t_hA	IORD-/IOWR- to address valid hold (min)	10	

1. t_{cyc} is the minimum total cycle time, t_w is the minimum command active time, and t_{rec} is the minimum command recovery time or command inactive time. The actual cycle time equals the sum of the actual command active time and the actual command inactive time. A host implementation must ensure that t_{cyc} is equal to or greater than the value reported in the devices IDENTIFY DEVICE data.

2. This parameter specifies the time from the negation edge of /IORD to the time that the data bus is no longer driven by the device (tri-state).

3.3.3.2. DMA Transfer Timing

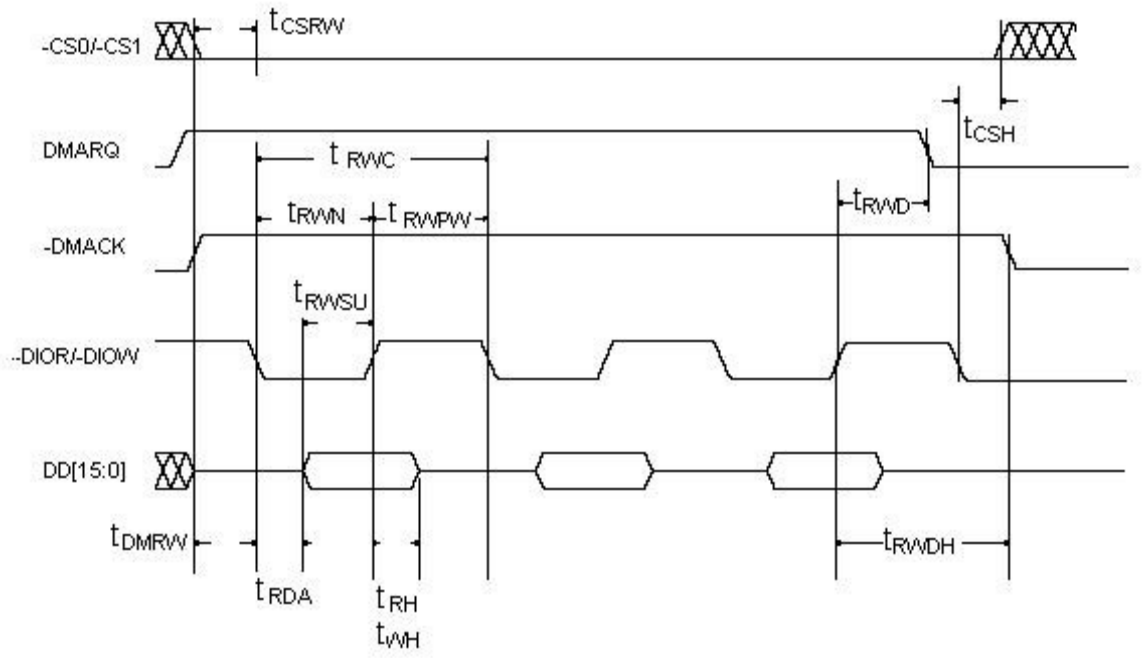


Figure 3-6. DMA Transfer To/From Device

DMA Timing Parameters		Mode 2 ns
Trwc	Cycle time (min)	100
$t_{su}A$	Address valid to IORD-/IOWR- setup (min)	65
T_{rwpw}	DIOR-/DIOW- pulse width high (min)	65
T_{dmrw}	DMACK to DIOR/DIOW setup (min)	0
trda	DIORD access time (max)	50
T_{rwsu}	DIOR/DIOW- data setup (min)	15
T_{wh}	DIOW- data hold (min)	5
Trwd	DIOW/DIOR to DMARQ delay (max)	35
T_{rwdh}	DIOR/DIOW to DMACK hold time (min)	5
T_{rh}	DIOR- data hold	5

	(min)	
Trwn	DIOR/DIOW pulse width low (min)	25
T_{csrw}	CS[1:0] valid to DIOR/DIOW (min)	10
tcsh	CS[1:0] hold time (min)	10

3.4. I/O Transfer Function

Table 3 -7defines the function of the operations for the DOM.

Table 3-7. FlashDrive I/O Function

Function Code	-CE2	-CE1	A0	-IORD	-IOWR	D15-D8	D7-D0
Invalid Mode	L	L	X	X	X	High Z	High Z
Standby Mode	H	H	X	X	X	High Z	High Z
Task File Write	H	L	1-7h	H	L	Do not care	Data In
Task File Read	H	L	1-7h	L	H	High Z	Data Out
Data Register Write	H	L	0	H	L	Odd-Byte In	Even-Byte In
Data Register Read	H	L	0	L	H	Odd-Byte Out	Even-Byte Out
Control Register Write	L	H	6h	H	L	Do not care	Control In
Alt Status Read	L	H	6h	L	H	High Z	Status Out

4. ATA Drive Register Set Definition and Protocol

The communication to or from the DOM is done using the Task File registers, which provide all the necessary registers for control and status information. The ATA interface connects peripherals to the host using four register mapping methods. Table 4 -7 is a detailed description of these methods.

Table 4-7. I/O Configurations

Address	Drive #	Description
1F0-1F7, 3F6-3F7	0	Primary I/O Mapped Drive 0
1F0-1F7, 3F6-3F7	1	Primary I/O Mapped Drive 1
170-177, 376-377	0	Secondary I/O Mapped Drive 0
170-177, 376-377	1	Secondary I/O Mapped Drive 1

4.1. Task File Addressing

I/O decoding to access the task file registers is as listed in Table 4 -8.

Table 4-8. Task File I/O Decoding

-CE2	-CE1	A2	A1	A0	-IORD=0	-IOWR=0
1	0	0	0	0	RD Data	WR Data
1	0	0	0	1	Error Register	Features
1	0	0	1	0	Sector Count	Sector Count
1	0	0	1	1	Sector No.	Sector No.
1	0	1	0	0	Cylinder Low	Cylinder Low
1	0	1	0	1	Cylinder High	Cylinder High
1	0	1	1	0	Select Drive/Head	Select Drive/Head
1	0	1	1	1	Status	Command
0	1	1	1	0	Alt Status	Device Control
0	1	1	1	1	Drive Address	Reserved

4.2. ATA Registers

4.2.1. Data Register (Address—1F0[170])

The Data Register is a 16-bit register, and it is used to transfer data blocks between the DOM data buffer and the Host.

4.2.2. Error Register (Address—1F1[171]; Read Only)

This register contains additional information about the source of an error when an error is indicated in bit 0 of the Status register. The bits are defined as follows:

D7	D6	D5	D4	D3	D2	D1	D0
BBK	UNC	0	IDNF	0	ABRT	0	AMNF

Bit 7 (BBK) This bit is set when a Bad Block is detected.
Bit 6 (UNC) This bit is set when an Uncorrectable Error is encountered.
Bit 5 This bit is 0.
Bit 4 (IDNF) The requested sector ID is in error or cannot be found.
Bit 3 This bit is 0.
Bit 2 (Abort) This bit is set if the command has been aborted because of a status condition: (Not Ready, Write Fault, etc.) or when an invalid command has been issued.
Bit 1 This bit is 0.
Bit 0 (AMNF) This bit is set in case of a general error.

4.2.3. Feature Register (Address—1F1[171]; Write Only)

This register provides information regarding features of the DOM that the host can utilize.

4.2.4. Sector Count Register (Address—1F2[172])

This register contains the number of sectors of data requested to be transferred on a read or write operation between the host and the DOM. If the value in this register is zero, a count of 256 sectors is specified. If the command was successful, this register is zero at command completion. If not successfully completed, the register contains the number of sectors that need to be transferred in order to complete the request.

4.2.5. Sector Number (LBA 7-0) Register (Address—1F3[173])

This register contains the starting sector number or bits 7-0 of the Logical Block Address (LBA) for any DOM data access for the subsequent command.

4.2.6. Cylinder Low (LBA 15-8) Register (Address—1F4[174])

This register contains the low order 8 bits of the starting cylinder address or bits 15-8 of the Logical Block Address.

4.2.7. Cylinder High (LBA 23-16) Register (Address—1F5[175])

This register contains the high order bits of the starting cylinder address or bits 23-16 of the Logical Block Address.

4.2.8. Drive/Head (LBA 27-24) Register (Address 1F6[176])

The Drive/Head register is used to select the drive and head. It is also used to select LBA addressing instead of cylinder/head/sector addressing. The bits are defined as follows:

D7	D6	D5	D4	D3	D2	D1	D0
1	LBA	1	DRV	HS3	HS2	HS1	HS0

Bit 7 This bit is set to 1.

Bit 6 LBA is a flag to select either Cylinder/Head/Sector (CHS) or Logical Block Address Mode (LBA). When LBA=0, Cylinder/Head/Sector mode is selected. When LBA=1, Logical Block Address is selected. In Logical Block Mode, the Logical Block Address is interpreted as follows:
LBA07-LBA00: Sector Number Register D7-D0.
LBA15-LBA08: Cylinder Low Register D7-D0.
LBA23-LBA16: Cylinder High Register D7-D0.
LBA27-LBA24: Drive/Head Register bits HS3-HS0.

Bit 5 This bit is set to 1.

Bit 4 (DRV) This bit will have the following meaning. DRV is the drive number. When DRV=0, drive 0 is selected When DRV=1, drive 1 is selected.

Bit 3 (HS3) When operating in the Cylinder, Head, Sector mode, this is bit 3 of the head number. It is Bit 27 in the Logical Block Address mode.

Bit 2 (HS2) When operating in the Cylinder, Head, Sector mode, this is bit 2 of the head number. It is Bit 26 in the Logical Block Address mode.

Bit 1 (HS1) When operating in the Cylinder, Head, Sector mode, this is bit 1 of the head number. It is Bit 25 in the Logical Block Address mode.

Bit 0 (HS0) When operating in the Cylinder, Head, Sector mode, this is bit 0 of the head number. It is Bit 24 in the Logical Block Address mode.

4.2.9. Status and Alternate Status Registers (Address 1F7[177] and 3F6[376])

These registers return the status when read by the host. Reading the Status register does clear a pending interrupt while reading the Auxiliary Status register does not. The meaning of the status bits are described as follows:

D7	D6	D5	D4	D3	D2	D1	D0
BUSY	RDY	DWF	DSC	DRQ	CORR	0	ERR

Bit 7 (BUSY) The busy bit is set when the device has access to the command buffer and registers and the host is locked out from accessing the command register and buffer. No other bits in this register are valid when this bit is set to a 1.

Bit 6 (RDY) RDY indicates whether the device is capable of performing operations requested by the host. This bit is cleared at power up and remains cleared until the device is ready to accept a command.

Bit 5 (DWF) This bit, if set, indicates a write fault has occurred.

Bit 4 (DSC) This bit is set when the device is ready.

Bit 3 (DRQ) The Data Request is set when the device requires that information be transferred either to or from the host through the Data register.

Bit 2 (CORR) This bit is set when a Correctable data error has been encountered and the data has been corrected. This condition does not terminate a multi-sector read operation.

Bit 1 (IDX) This bit is always set to 0.

Bit 0 (ERR) This bit is set when the previous command has ended in some type of error. The bits in the Error register contain additional information describing the error.

4.2.10. Device Control Register (Address—3F6[376])

This register is used to control the drive interrupt request and to issue an ATA soft reset to the drive. The bits are defined as follows:

D7	D6	D5	D4	D3	D2	D1	D0
X	X	X	X	1	SW Rst	-IEn	0

Bit 7 This bit is an X (Do not care).

Bit 6 This bit is an X (Do not care).

Bit 5 This bit is an X (Do not care).

Bit 4 This bit is an X (Do not care).

Bit 3 This bit is ignored by the drive.

Bit 2 (SW Rst) This bit is set to 1 in order to force the drive to perform an AT Disk controller Soft Reset operation. The drive remains in Reset until this bit is reset to '0'.

Bit 1 (-IEn) The Interrupt Enable bit enables interrupts when the bit is 0. When the bit is 1, interrupts from the drive are disabled. This bit is set to 0 at power on and Reset.

Bit 0 This bit is ignored by the drive.

4.2.11. Drive Address Register (Address 3F7[377])

This register is provided for compatibility with the AT disk drive interface. It is recommended that this register not be mapped into the host's I/O space because of potential conflicts on Bit 7. The bits are defined as follows:

D7	D6	D5	D4	D3	D2	D1	D0
X	-WTG	-HS3	-HS2	-HS1	-HS0	-nDS1	-nDS0

Bit 7 This bit is unknown.

Implementation Note:
Conflicts may occur on the host data bus when this bit is provided by a Floppy Disk Controller operating at the same addresses as the DOM. Following are some possible solutions to this problem:

1. Locate the DOM at a non-conflicting address (i.e., Secondary address (377) when a Floppy Disk Controller is located at the Primary addresses).
2. Do not install a Floppy and a DOM in the system at the same time.
3. Implement a socket adapter that can be programmed to (conditionally) tri-state D7 of I/0 address 3F7/377 when a DOM product is installed and conversely to tri-state D6-D0 of I/O address 3F7/377 when a floppy controller is installed.
4. Do not use the DOM's Drive Address register. This may be accomplished by either a) If possible, program the host adapter to enable only I/O addresses 1F0-1F7, 3F6 (or 170-177, 176) to the DOM or b) if provided use an additional Primary/Secondary configuration in the DOM that does not respond to accesses to I/O locations 3F7 and 377. With either of these implementations, the host software must not attempt to use information in the Drive Address Register.

Bit 6 (-WTG) This bit is 0 when a write operation is in progress, otherwise, it is 1.
Bit 5 (-HS3) This bit is the negation of bit 3 in the Drive/Head register.
Bit 4 (-HS2) This bit is the negation of bit 2 in the Drive/Head register.
Bit 3 (-HS1) This bit is the negation of bit 1 in the Drive/Head register.
Bit 2 (-HS0) This bit is the negation of bit 0 in the Drive/Head register.
Bit 1 (-nDS1) This bit is 0 when drive 1 is active and selected.
Bit 0 (-nDS0) This bit is 0 when the drive 0 is active and selected.

5. ATA Command Description

This section defines the software requirements and the format of the commands the host sends to the Industrial DOM products. Commands are issued by loading the required registers in the command block with the supplied parameters, and then writing the command code to the Command Register. The manner in which a command is accepted varies. There are three classes (see Table 5 -9) of command acceptance, all dependent on the host not issuing commands unless the drive is not busy. (The BUSY bit in the status and alternate status registers is 0.)

- Upon receipt of a Class 1 command, the drive sets the BUSY bit within 400 nsec.
- Upon receipt of a Class 2 command, the drive sets the BUSY bit within 400 nsec, sets up the sector buffer for a write operation, sets DRQ within 700 µsec, and clears the BUSY bit within 400 nsec of setting DRQ.
- Upon receipt of a Class 3 command, the drive sets the BUSY bit within 400 nsec, sets up the sector buffer for a write operation, sets DRQ within 20 msec (assuming no re-assignments), and clears the BUSY bit within 400 nsec of setting DRQ.

5.1. ATA Command Set

Table 5 -9 summarizes the ATA command set with the paragraphs that follow describing the individual commands and the task file for each.

Table 5-9. ATA Command Set

Class	COMMAND	Code	FR	SC	SN	CY	DH	LBA
1	Check Power Mode	E5h or 98h	-	-	-	-	D	-
1	Execute Drive Diagnostic	90h	-	-	-	-	D	-
1	Erase Sector(s)	C0h	-	Y	Y	Y	Y	Y
2	Format Track	50h	-	Y	-	Y	Y	Y
1	Identify Drive	ECh	-	-	-	-	D	-
1	Idle	E3h or 97h	-	Y	-	-	D	-
1	Idle Immediate	E1h or 95h	-	-	-	-	D	-
1	Initialize Drive Parameters	91h	-	Y	-	-	Y	-
1	Read Buffer	E4h	-	-	-	-	D	-
1	Read Multiple	C4h	-	Y	Y	Y	Y	Y
1	Read Long Sector	22h or 23h	-	-	Y	Y	Y	Y
1	Read Sector(s)	20h or 21h	-	Y	Y	Y	Y	Y
1	Read Verify Sector(s)	40h or 41h	-	Y	Y	Y	Y	Y

Class	COMMAND	Code	FR	SC	SN	CY	DH	LBA
1	Recalibrate	1Xh	-	-	-	-	D	-
1	Request Sense	03h	-	-	-	-	D	-
1	Seek	7Xh	-	-	Y	Y	Y	Y
1	Set Features	EFh	Y	-	-	-	D	-
1	Set Multiple Mode	C6h	-	Y	-	-	D	-
1	Set Sleep Mode	E6h or 99h	-	-	-	-	D	-
1	Stand By	E2h or 96h	-	-	-	-	D	-
1	Stand By Immediate	E0h or 94h	-	-	-	-	D	-
1	Translate Sector	87h	-	Y	Y	Y	Y	Y
1	Wear Level	F5h	-	-	-	-	Y	-
2	Write Buffer	E8h	-	-	-	-	D	-
2	Write Long Sector	32h or 33h	-	-	Y	Y	Y	Y
3	Write Multiple	C5h	-	Y	Y	Y	Y	Y
3	Write Multiple w/o Erase	CDh	-	Y	Y	Y	Y	Y
2	Write Sector(s)	30h or 31h	-	Y	Y	Y	Y	Y
2	Write Sector(s) w/o Erase	38h	-	Y	Y	Y	Y	Y
2	Write Verify Sector(s)	3Ch	-	Y	Y	Y	Y	Y

Definitions: FR = Features Register, SC = Sector Count Register, SN = Sector Number Register, CY = Cylinder Registers, DH = Drive/Drive/Head Register, LBA = Logical Block Address Mode Supported (see command descriptions for use).
Y—The register contains a valid parameter for this command. For the Drive/Head Register Y means both the drive and head parameters are used; D—only the drive parameter is valid and not the head parameter.

5.1.1. Check Power Mode—98H, E5H

The Check Power Mode command in Table 5 -10 checks the power mode.

Table 5-10. Check Power Mode

Bit ->	7	6	5	4	3	2	1	0
Command (7)	E5H or 98H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							

Sec Cnt (2)	X
Feature (1)	X

If the drive is in, going to, or recovering from the standby mode, the drive sets BSY, sets the Sector Count Register to 00h, clears BSY and generates an interrupt. If the drive is in active mode, the drive sets BSY, sets the Sector Count Register to FFh, clears BSY and generates an interrupt.

5.1.2. Execute Drive Diagnostic—90H

The Executive Drive Diagnostic command in Table 5 -11 performs the internal diagnostic tests implemented by the drive.

Table 5-11. Executive Drive Diagnostic

Bit ->	**7**	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Command (7)	90H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	X							

A code of 01h will be returned in the Error Register at the end of the command.

5.1.3. Erase Sector(s)—C0H

Table 5-12. Erase Sectors

Bit ->	**7**	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Command (7)	C0H							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							

Sec Num (3)	Sector Number (LBA 7-0)
Sec Cnt (2)	Sector Count
Feature (1)	X

The sectors indicated in the task file are left in erased states. This command is used in advanced of a write w/o erase or write multiple w/o erase command. Erased sectors return all zero data when read.

5.1.4. Format Track—50H

Table 5-13. Format Track

Bit ->	**7**	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Command (7)	50H							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	X (LBA 7-0)							
Sec Cnt (2)	Count (LBA mode only)							
Feature (1)	X							

This command writes the desired head and cylinder of the selected drive with a vendor unique pattern. To remain host backward compatible, the drive expects a sector buffer of data from the host to follow the command with the same protocol as the Write Sector(s) command although the information in the buffer is not used by the drive. If LBA=1 then the number of sectors to format is taken from the Sec Cnt register (0=256).

5.1.5. Identify Drive—ECH

The Identify Drive command in Table 5 -14 enables the host to receive parameter information from the drive. This command has the same protocol as the Read Sector(s) command. The parameter words in the buffer have the arrangement and meanings defined in Table 5 -15. All reserved bits or words are zero. Table 5 -15 is the definition for each field in the Identify Drive Information.

Table 5-14. Identify Drive

Bit ->	**7**	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Command (7)	ECH							

C/D/H (6)	X	X	X	Drive	X
Cyl High (5)	X				
Cyl Low (4)	X				
Sec Num (3)	X				
Sec Cnt (2)	X				
Feature (1)	X				

Table 5-15. Identify Drive Information

Word Address	Default Value	Total Bytes	Data Field Type Information
0	044AH	2	General configuration bit-significant information.
1	01EFH	2	Default number of cylinders.
2	0000H	2	Reserved.
3	0004H	2	Default number of heads.
4	0000H	2	Number of unformatted bytes per track.
5	0200H	2	Number of unformatted bytes per sector.
6	0020H	2	Default number of sectors per track.
7-8	0000H,F780H	4	Number of sectors per drive (Word 7 = MSW, Word 8 = LSW).
9	0000H	2	Reserved.
10-19	aaaa	20	Serial number in ASCII (Right Justified).
20	0001H	2	Buffer type (single port).
21	0001H	2	Buffer size in 512 byte increments.
22	0004H	2	Number of ECC bytes passed on Read/Write Long Commands.
23-26	aaaa	8	Firmware revision in ASCII . Big Endian Byte Order in Word.
27-46	aaaa	40	Model number in ASCII (Left Justified) Big Endian Byte Order in Word.
47	0001H	2	Maximum of 1 sector on Read/Write Multiple command.
48	0000H	2	Double Word not supported.
49	0F00H	2	Capabilities: DMA Supported in True IDE mode (bit 8), LBA supported (bit 9).
50	0000H	2	Reserved.
51	0200H	2	PIO data transfer cycle timing mode
52	0000H	2	Single Word DMA data transfer cycle timing mode (not supported).
53	0001H	2	Data fields 54-58 are valid.
54	XXXX	2	Current numbers of cylinders.
55	XXXX	2	Current numbers of heads.

Word Address	Default Value	Total Bytes	Data Field Type Information
56	XXXX	2	Current sectors per track.
57-58	XXXX	4	Current capacity in sectors (LBAs) (Word 57 = LSW, Word 58 = MSW).
59	0100H	2	Multiple sector setting is valid.
60-61	XXXX	4	Total number of sectors addressable in LBA Mode.
62-63	0000H	2	Reserved
64	0003H	1	Advanced PIO modes supported (modes 3 and 4)
65-255	0000H	2	Reserved

5.1.5.1. Word 0: General Configuration

This field informs the host that this is a non-magnetic, hard sectored, removable storage device with a transfer rate greater than 10 mb/sec and is not MFM encoded.

5.1.5.2. Word 1: Default Number of Cylinders

This field contains the number of translated cylinders in the default translation mode. This value will be the same as the number of cylinders.

5.1.5.3. Word 3: Default Number of Heads

This field contains the number of translated heads in the default translation mode.

5.1.5.4. Word 4: Number of Unformatted Bytes per Track

This field contains the number of unformatted bytes per translated track in the default translation mode.

5.1.5.5. Word 5: Number of Unformatted Bytes per Sector

This field contains the number of unformatted bytes per sector in the default translation mode.

5.1.5.6. Word 6: Default Number of Sectors per Track

This field contains the number of sectors per track in the default translation mode.

5.1.5.7. Words 7-8: Number of Sectors per drive

This field contains the number of sectors per drive. This double word value is also the first invalid address in LBA translation mode.

5.1.5.8. Words 10-19: Drive Serial Number

The contents of this field are right justified and padded with spaces (20h).

5.1.5.9. Word 20: Buffer Type

This field defines the buffer capability with the 0001h meaning a single ported multi-sector buffer capable of single source data transfers to or from either the host or the drive.

5.1.5.10. Word 21: Buffer Size

This field defines the buffer capacity of 1 sector or 512 bytes of SRAM.

5.1.5.11. Word 22: ECC Count

This field defines the number of ECC bytes used on each sector in the Read and Write Long commands.

5.1.5.12. Words 23-26: Firmware Revision

This field contains the revision of the firmware for this product.

5.1.5.13. Words 27-46: Model Number

This field contains the model number for this product and is left justified and padded with spaces (20h).

5.1.5.14. Word 47: Read/Write Multiple Sector Count

This field contains the maximum number of sectors that can be read or written per interrupt using the Read Multiple or Write Multiple commands.

5.1.5.15. Word 48: Double Word Support

This field indicates this product will not support double word transfers.

5.1.5.16. Word 49: Capabilities

This field indicates if this product supports DMA Data transfers and LBA mode. All Cactus Technologies® products support LBA mode. Multiword DMA operation is also supported.

5.1.5.17. Word 51: PIO Data Transfer Cycle Timing Mode

This field indicated the supported PIO transfer timing for the DOM.

NOTE: For backward compatibility with BIOSs written before Word 64 was defined for advanced modes, a device reports in Word 51 the highest original PIO mode it can support (i.e., PIO mode 0, 1 or 2).

5.1.5.18. Word 52: Single Word DMA Data Transfer Cycle Timing Mode

This field states this product doesn't support Single Word DMA data transfer mode.

5.1.5.19. Word 53: Translation Parameters Valid

Bit 0 of this field is set, indicating that words 54 to 58 are valid and reflect the current number of cylinders, heads and sectors. Bit 1 is also set, indicating values in words 64 through 70 are valid.

5.1.5.20. Words 54-56: Current Number of Cylinders, Heads, Sectors/Track

These fields contain the current number of user addressable Cylinders, Heads, and Sectors/Track in the current translation mode.

5.1.5.21. Words 57-58: Current Capacity

This field contains the product of the current cylinders times heads times sectors.

5.1.5.22. Word 59: Multiple Sector Setting

This field contains a validity flag in the odd byte and the current number of sectors that can be transferred per interrupt for R/W Multiple in the even byte. The odd byte is always 01H, which indicates that the even byte is always valid.

The even byte value depends on the value set by the Set Multiple command. The even byte of this word by default contains a 00H, which indicates that R/W Multiple commands are not valid. The only other value returned by the drive in the even byte is a 01H value, which indicates that 1 sector per interrupt, can be transferred in R/W Multiple mode.

5.1.5.23. Words 60-61: Total Sectors Addressable in LBA Mode

This field contains the number of sectors addressable for the drive in LBA mode only.

5.1.5.24. Word 64: Advanced PIO Transfer Modes Supported

Bits 0 and 1 of this field are set to indicate support for PIO transfer modes 3 and 4, respectively.

5.1.6. Idle—97H, E3H

These commands are treated as NOPs by the drive. Since the drive goes into sleep mode after every command, these extra IDLE commands are redundant.

Table 5-16. Idle

Bit ->	7	6	5	4	3	2	1	0
Command (7)	E3H or 97H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.7. Idle Immediate—95H, E1H

Table 5-17. Idle Immediate

Bit ->	7	6	5	4	3	2	1	0
Command (7)	E1H or 95H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.8. Initialize Drive Parameters—91H

The Initialize Drive Parameters command in Table 5 -18 causes the drive to set BSY, enter the Idle (Read) mode, clear BSY and generate an interrupt. This command enables the host to set the number of sectors per track and the number of heads per cylinder. Only the Sector Count and the Drive/Drive/Head registers are used by this command.

Table 5-18. Initialize Drive Parameters

Bit ->	7	6	5	4	3	2	1	0
Command (7)	91H							
C/D/H (6)	X	0	X	Drive	Max Head (no. of heads-1)			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	Number of Sectors							
Feature (1)	X							

5.1.9. Read Buffer—E4H

The Read Buffer command in Table 5 -19 enables the host to read the current contents of the DOM's sector buffer. This command has the same protocol as the Read Sector(s) command.

Table 5-19. Read Buffer

Bit ->	7	6	5	4	3	2	1	0
Command (7)	E4H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.10. Read Multiple—C4H

The Read Multiple command in Table 5 -20 performs similarly to the Read Sectors command. Interrupts are not generated on every sector, but on the transfer of a block, which contains the number of sectors defined by a Set Multiple, command.

Table 5-20. Read Multiple

Bit ->	7	6	5	4	3	2	1	0
Command (7)	C4H							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	Sector Number (LBA 7-0)							
Sec Cnt (2)	Sector Count							
Feature (1)	X							

Command execution is identical to the Read Sectors operation except that the number of sectors defined by a Set Multiple command is transferred without intervening interrupts. DRQ qualification of the transfer is required only at the start of the data block, not on each sector.

The block count of sectors to be transferred without intervening interrupts is programmed by the Set Multiple Mode command, which must be executed prior to the Read Multiple command. When the Read Multiple command is issued, the Sector Count Register contains the number of sectors (not the number of blocks or the block count) requested. If the number of requested sectors is not evenly divisible by the block count, as many full blocks as possible are transferred, followed by a final, partial block transfer. The partial block transfer is for n sectors, where:

n = (sector count)—module (block count).

If the Read Multiple command is attempted before the Set Multiple Mode command has been executed or when Read Multiple commands are disabled, the Read Multiple operation is rejected with an Aborted Command error. Disk errors encountered during Read Multiple commands are posted at the beginning of the block or partial block transfer, but DRQ is still set and the data transfer will take place as it normally would, including transfer of corrupted data, if any.

Interrupts are generated when DRQ is set at the beginning of each block or partial block. The error reporting is the same as that on a Read Sector(s) Command. This command reads from 1 to 256 sectors as specified in the Sector Count register. A sector count of 0 requests 256 sectors. The transfer begins at the sector specified in the Sector Number Register.

At command completion, the Command Block Registers contain the cylinder, head and sector number of the last sector read. If an error occurs, the read terminates at the sector where the error occurred. The Command Block Registers contain the cylinder, head and sector number of the sector where the error occurred. The flawed data is pending in the sector buffer.

Subsequent blocks or partial blocks are transferred only if the error was a correctable data error. All other errors cause the command to stop after transfer of the block that contained the error.

5.1.11. Read Long Sector—22H, 23H

The Read Long command in Table 5 -21 performs similarly to the Read Sector(s) command except that it returns 516 bytes of data instead of 512 bytes. During a Read Long command, the drive does not check the ECC bytes to determine if there has been a data error. Only single sector read long operations are supported. The transfer consists of 512 bytes of data transferred in word mode followed by 4 bytes of random data transferred in byte mode. Random data is returned instead of ECC bytes because of the nature of the ECC system used. This command has the same protocol as the Read Sector(s) command.

Table 5-21. Read Long Sector

Bit ->	7	6	5	4	3	2	1	0
Command (7)	22H or 23H							

C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	Sector Number (LBA 7-0)							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.12. Read Sector(s)—20H, 21H

The Read Sector(s) command in Table 5 -22 reads from 1 to 256 sectors as specified in the Sector Count register. A sector count of 0 requests 256 sectors. The transfer begins at the sector specified in the Sector Number Register. When this command is issued and after each sector of data (except the last one) has been read by the host, the drive sets BSY, puts the sector of data in the buffer, sets DRQ, clears BSY, and generates an interrupt. The host then reads the 512 bytes of data from the buffer.

At command completion, the Command Block Registers contain the cylinder, head and sector number of the last sector read. If an error occurs, the read terminates at the sector where the error occurred. The Command Block Registers contain the cylinder, head, and sector number of the sector where the error occurred. The flawed data is pending in the sector buffer.

Table 5-22. Read Sectors

Bit ->	**7**	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Command (7)	20H or 21H							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	Sector Number (LBA 7-0)							
Sec Cnt (2)	Sector Count							
Feature (1)	X							

5.1.13. Read Verify Sector(s)—40H, 41H

The Read Verify Sector(s) command in Table 5 -23 is identical to the Read Sectors command, except that DRQ is never set and no data is transferred to the host. When the command is accepted, the drive sets BSY.

When the requested sectors have been verified, the drive clears BSY and generates an interrupt. Upon command completion, the Command Block Registers contain the cylinder, head, and sector number of the last sector verified.

If an error occurs, the verify terminates at the sector where the error occurs. The Command Block Registers contain the cylinder, head and sector number of the sector where the error occurred. The Sector Count Register contains the number of sectors not yet verified.

Table 5-23. Read Verify Sectors

Bit ->	7	6	5	4	3	2	1	0
Command (7)	40H or 41H							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	Sector Number (LBA 7-0)							
Sec Cnt (2)	Sector Count							
Feature (1)	X							

5.1.14. Recalibrate—1XH

The Recalibrate command in Table 5 -24 is effectively a NOP command to the drive and is provided for compatibility purposes. After this command is executed the Cyl High and Cyl Low as well as the Head number will be 0 and Sec Num will be 1 if LBA=0 and 0 if LBA=1 (i.e., the first block in LBA is 0 while CHS mode the sector number starts at 1).

Table 5-24. Recalibrate

Bit ->	7	6	5	4	3	2	1	0
Command (7)	1XH							
C/D/H (6)	1	LBA	1	Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							

Sec Num (3)	X
Sec Cnt (2)	X
Feature (1)	X

5.1.15. Request Sense—03H

The Request Sense command in Table 5 -25 requests an extended error code after a command ends with an error.

Table 5-25. Request Sense

Bit ->	**7**	**6**	**5**	**4**	**3**	**2**	**1**	**0**
Command (7)	03H							
C/D/H (6)	1	X	1	Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	X							

Table 5 -26 defines the valid extended error codes for Cactus Technologies® Industrial DOM products. The extended error code is returned to the host in the Error Register. This command must be the next command issued to the drive following the command that returned an error.

Table 5-26. Extended Error Codes

Extended Error Code	Description
01h	Self Test OK (No Error)
03h	Write Failed
09h	Miscellaneous Error
11h	Uncorrectable ECC Error
18h	Corrected ECC Error
20h	Invalid Command
21h	Invalid Address
27h	Write Protection Violation

5.1.16. Seek—7XH

The Seek command in Table 5 -27 is effectively a NOP command to the drive although it does perform a range check of cylinder and head or LBA address and returns an error if the address is out of range.

Table 5-27. Seek

Bit ->	7	6	5	4	3	2	1	0
Command (7)	7XH							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	X (LBA 7-0)							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.17. Set Features—EFH

The Set Features command in Table 5 -28 is used by the host to establish or select certain features.

Table 5-28. Seat Features

Bit ->	7	6	5	4	3	2	1	0
Command (7)	EFH							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	Feature							

Table 5 -29 defines all features that are supported.

Table 5-29. Features Supported

Feature	Operation
01H	Enable 8-bit data transfer.
55H	Disable Read Look Ahead.
66H	Disable Power on Reset (POR) establishment of defaults at Soft Reset.
69H	NOP; accepted for backward compatibility.
81H	Disable 8-bit data transfer.
96H	NOP; accepted for backward compatibility.
97H	NOP; accepted for backward compatibility.
BBH	4 bytes of data apply on Read/Write Long commands.
CCH	Enable Power on Reset (POR) establishment of defaults at Soft Reset.

Features 01H and 81H are used to enable and clear 8 bit data transfer mode. If the 01H feature command is issued, all data transfers will occur on the low order D7-D0 data bus and the IOIS16 signal will not be asserted for data register accesses.

Features 55H and BBH are the default features for the drive; thus, the host does not have to issue this command with these features unless it is necessary for compatibility reasons.

Features 66H and CCH can be used to enable and disable whether the Power On Reset (POR) Defaults will be set when a soft reset occurs. The default setting is to revert to the POR defaults when a soft reset occurs. POR defaults the number of heads and sectors along with 16 bit data transfers and the read/write multiple block count.

5.1.18. Set Multiple Mode—C6H

The Set Multiple Mode command in Table 5 -30 enables the drive to perform Read and Write Multiple operations and establishes the block count for these commands. The Sector Count Register is loaded with the number of sectors per block. Upon receipt of the command, the DOM sets BSY to 1 and checks the Sector Count Register.

Table 5-30. Seat Multiple Mode

Bit ->	7	6	5	4	3	2	1	0
Command (7)	C6H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	Sector Count							
Feature (1)	X							

If the Sector Count Register contains a valid value and the block count is supported, the value is loaded for all subsequent Read Multiple and Write Multiple commands and execution of those commands is enabled. If a block count is not supported, an Aborted Command error is posted, and Read Multiple and Write Multiple commands are disabled. If the Sector Count Register contains 0 when the command is issued, Read and Write Multiple commands are disabled. At power on, or after a hardware or (unless disabled by a Set Feature command) software reset, the default mode is Read and Write Multiple disabled.

5.1.19. Set Sleep Mode- 99H, E6H

These commands are treated as NOPs by the drive. Since the drive goes into sleep mode after every command execution, these extra SLEEP commands are redundant.

Table 5-31. Set Sleep Mode

Bit ->	7	6	5	4	3	2	1	0
Command (7)	E6H or 99H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.20. Standby—96H, E2H

The Standby and Standby Immediate commands are treated as NOPs by the drive. Since the drive goes into sleep mode after every command execution, these extra Standby commands are redundant.

Table 5-32. Standby

Bit ->	7	6	5	4	3	2	1	0
Command (7)	E2H or 96H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.21. Standby Immediate—94H, E0H

Table 5-33. Standby Immediate

Bit ->	7	6	5	4	3	2	1	0
Command (7)	E0H or 94H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.22. Translate Sector—87H

This is a NOP command for the drive. The sector count register will always return 0.

Table 5-34. Translate Sector

Bit ->	7	6	5	4	3	2	1	0
Command (7)	87H							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	Sector Number (LBA 7-0)							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.23. Wear Level—F5H

The Wear Level command in Table 5 -35 is effectively a NOP command and only implemented for backward compatibility. The Sector Count Register will always be returned with a 00H indicating Wear Level is not needed.

Table 5-35. Wear Level

Bit ->	7	6	5	4	3	2	1	0
Command (7)	F5H							
C/D/H (6)	X	X	X	Drive	Flag			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	Completion Status							
Feature (1)	X							

5.1.24. Write Buffer—E8H

The Write Buffer command in Table 5 -36 enables the host to overwrite contents of the drive's sector buffer with any data pattern desired. This command has the same protocol as the Write Sector(s) command and transfers 512 bytes.

Table 5-36. Write Buffer

Bit ->	7	6	5	4	3	2	1	0
Command (7)	E8H							
C/D/H (6)	X			Drive	X			
Cyl High (5)	X							
Cyl Low (4)	X							
Sec Num (3)	X							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.25. Write Long Sector—32H, 33H

The Write Multiple command in Table 5 -37 is provided for compatibility purposes and is similar to the Write Sector(s) command except that it writes 516 bytes instead of 512 bytes. Only single sector Write Long operations are supported. The transfer consists of 512 bytes of data transferred in word mode followed by 4 bytes of vendor unique data supplied by the host. The drive discards these four bytes and writes the sector with valid ECC fields. This command has the same protocol as the Write Sector(s) command.

Table 5-37. Write Long Sector

Bit ->	7	6	5	4	3	2	1	0
Command (7)	32H or 33H							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	Sector Number (LBA 7-0)							
Sec Cnt (2)	X							
Feature (1)	X							

5.1.26. Write Multiple Command—C5H

The Write Multiple command in Table 5 -38 is similar to the Write Sectors command. The drive sets BSY within 400 nsec of accepting the command. Interrupts are not presented on each sector but on the transfer of a block that contains the number of sectors defined by Set Multiple. Command execution is identical to the Write Sectors operation except that the number of sectors defined by the Set Multiple command is transferred without intervening interrupts.

Table 5-38. Write Multiple Command

Bit ->	7	6	5	4	3	2	1	0
Command (7)	C5H							
C/D/H (6)	X	LBA	X	Drive	Head			
Cyl High (5)	Cylinder High							
Cyl Low (4)	Cylinder Low							
Sec Num (3)	Sector Number							
Sec Cnt (2)	Sector Count							
Feature (1)	X							

DRQ qualification of the transfer is required only at the start of the data block, not on each sector. The block count of sectors to be transferred without intervening interrupts is programmed by the Set Multiple Mode command, which must be executed prior to the Write Multiple command.

When the Write Multiple command is issued, the Sector Count Register contains the number of sectors (not the number of blocks or the block count) requested. If the number of requested sectors is not evenly divisible by the sector/block, as many full blocks as possible are transferred, followed by a final, partial block transfer. The partial block transfer is for n sectors, where:

n = remainder (sector count/block count).

If the Write Multiple command is attempted before the Set Multiple Mode command has been executed or when Write Multiple commands are disabled, the Write Multiple operation will be rejected with an aborted command error.

Errors encountered during Write Multiple commands are posted after the attempted writes of the block or partial block transferred. The Write command ends with the sector in error, even if it is in the middle of a block. Subsequent blocks are not transferred in the event of an error. Interrupts are generated when DRQ is set at the beginning of each block or partial block.

The Command Block Registers contain the cylinder, head and sector number of the sector where the error occurred and the Sector Count Register contains the residual number of sectors that need to be transferred for successful completion of the command e.g., each block has 4 sectors, a request for 8 sectors is issued and an error occurs on the third sector. The Sector Count Register contains 6 and the address is that of the third sector.

5.1.27. Write Multiple without Erase—CDH

This command is similar to the Write Multiple command except that an implied erase is not performed.

Table 5-39. Write Multiple without Erase

Bit ->	7	6	5	4	3	2	1	0
Command (7)	CDH							
C/D/H (6)	X	LBA	X	Drive	Head			
Cyl High (5)	Cylinder High							
Cyl Low (4)	Cylinder Low							
Sec Num (3)	Sector Number							
Sec Cnt (2)	Sector Count							
Feature (1)	X							

5.1.28. Write Sector(s)—30H, 31H

The Write Sectors command in Table 5 -40 writes from 1 to 256 sectors as specified in the Sector Count Register. A sector count of zero requests 256 sectors. The transfer begins at the sector specified in the Sector Number Register. When this command is accepted, the drive sets BSY, then sets DRQ and clears BSY, then waits for the host to fill the sector buffer with the data to be written. No interrupt is generated to start the first buffer fill operation. No data should be transferred by the host until BSY has been cleared by the host.

Table 5-40. Write Sectors

Bit ->	7	6	5	4	3	2	1	0
Command (7)	30H or 31H							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	Sector Number (LBA 7-0)							
Sec Cnt (2)	Sector Count							
Feature (1)	X							

For multiple sectors, after the first sector of data is in the buffer, BSY will be set and DRQ will be cleared. After the next buffer is ready for data, BSY is cleared, DRQ is set and an interrupt is generated. When the final sector of data is transferred, BSY is set and DRQ is cleared. It will remain in this state until the command is completed at which time BSY is cleared and an interrupt is generated.

If an error occurs during a write of more than one sector, writing terminates at the sector where the error occurs. The Command Block Registers contain the cylinder, head and sector number of the sector where the error occurred. The host may then read the command block to determine what error has occurred, and on which sector.

5.1.29. Write Sector(s) without Erase—38H

This command is similar to the Write Sector command except that an implied erase is not performed.

Table 5-41. Write Sectors without Erase

Bit ->	7	6	5	4	3	2	1	0
Command (7)	38H							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	Sector Number (LBA 7-0)							
Sec Cnt (2)	Sector Count							
Feature (1)	X							

5.1.30. Write Verify Sector(s)—3CH

The Write Verify Sector(s) command in Table 5 -42 writes and verifies from 1 to 256 sectors as specified in the Sector Count Register. A sector count of zero requests 256 sectors. The transfer begins at the sector specified in the Sector Number Register. When this command is accepted, the drive sets BSY, then sets DRQ and clears BSY, then waits for the host to fill the sector buffer with the data to be written. No interrupt is generated to start the first buffer fill operation. No data should be transferred by the host until BSY has been cleared by the host.

Table 5-42. Writer Verify Sectors

Bit ->	7	6	5	4	3	2	1	0
Command (7)	3CH							
C/D/H (6)	1	LBA	1	Drive	Head (LBA 27-24)			
Cyl High (5)	Cylinder High (LBA 23-16)							
Cyl Low (4)	Cylinder Low (LBA 15-8)							
Sec Num (3)	Sector Number (LBA 7-0)							
Sec Cnt (2)	Sector Count							
Feature (1)	X							

For multiple sectors, after the first sector of data is in the buffer, BSY will be set and DRQ will be cleared. After the next buffer is ready for data, BSY is cleared, DRQ is set and an interrupt is generated. When the final sector of data is transferred, BSY is set and DRQ is cleared. It will remain in this state until the command is completed at which time BSY is cleared and an interrupt is generated.

If an error occurs during a write of more than one sector, writing terminates at the sector where the error occurs. The Command Block Registers contain the cylinder, head and sector number of the sector where the error occurred. The host may then read the command block to determine what error has occurred, and on which sector.

5.2. Error Posting

Table 5 -43 summarizes the valid status and error value for all the ATA Command set.

Table 5-43. Error and Status Register

Command	Error Register					Status Register				
	BBK	UNC	IDNF	ABRT	AMNF	DRDY	DWF	DSC	CORR	ERR
Check Power Mode				V		V	V	V		V
Execute Drive Diagnostic(1)						V		V		V

Command	Error Register					Status Register				
	BBK	UNC	IDNF	ABRT	AMNF	DRDY	DWF	DSC	CORR	ERR
Erase Sector(s)	V		V	V	V	V	V	V		V
Format Track			V	V	V	V	V	V		V
Identify Drive				V		V	V	V		V
Idle				V		V	V	V		V
Idle Immediate				V		V	V	V		V
Initialize Drive Parameters						V		V		V
Read Buffer				V		V	V	V		V
Read DMA	V	V	V	V	V	V	V	V	V	V
Read Multiple	V	V	V	V	V	V	V	V	V	V
Read Long Sector	V		V	V	V	V	V	V		V
Read Sector(s)	V	V	V	V	V	V	V	V	V	V
Read Verify Sectors	V	V	V	V	V	V	V	V	V	V
Recalibrate				V		V	V	V		V
Request Sense				V		V		V		V
Seek			V	V		V	V	V		V
Set Features				V		V	V	V		V
Set Multiple Mode				V		V	V	V		V
Set Sleep Mode				V		V	V	V		V
Stand By				V		V	V	V		V
Stand By Immediate				V		V	V	V		V
Translate Sector	V		V	V	V	V	V	V		V
Wear Level	V	V	V	V	V	V	V	V		V
Write Buffer				V		V	V	V		V
Write DMA	V		V	V		V	V			V
Write Long Sector	V		V	V	V	V	V	V		V
Write Multiple	V		V	V	V	V	V	V		V
Write Multiple w/o Erase	V		V	V	V	V	V	V		V
Write Sector(s)	V		V	V	V	V	V	V		V
Write Sector(s) w/o Erase	V		V	V	V	V	V	V		V
Write Verify Sector(s)	V		V	V	V	V	V	V		V
Invalid Command Code				V		V	V	V		V

[1] See Table 5 -10.

V = valid on this command.

Appendix A. Ordering Information

A.1. DOM

Model KMXY-203-Z

Where: X is drive capacities:

128M ---------- 128MB
256M ---------- 256MB
512M ---------- 512MB
1G ---------- 1GB

Where Y is temperature

Blank ---------- Standard temperature (0° C to +70° C)
I ---------- Extended temperature (-45° C to +90° C)

Where Z is form factor

A ---------- 40-Pin DOM
B ---------- 44-Pin DOM

Example:

(1) 512MB 40-Pin DOM ---------- KM512M-203-A
(2) 1GB 44-Pin DOM Extended Temp ---------- KM1GI-203-B

Appendix B. Technical Support Services

B.1. Direct Cactus Technical Support

Cactus Technologies Limited
Suite C, 15/F, Capital Trade Center
62 Tsun Yip Street, Kwun Tong
Kowloon, Hong Kong

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Fax: +852-27973777
Email: sales@cactus-tech.com

Appendix C. Cactus Worldwide Sales Offices

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Email: sales@cactus-tech.com

US Office:

Cactus USA
3112 Windsor Road , Suite A356
Austin, Texas 78703
Tel: (512) 775 0746
Email: americas@cactus-tech.com

Appendix D. Limited Warranty

I. WARRANTY STATEMENT

Cactus Technologies® warrants its Industrial Grade products only to be free of any defects in materials or workmanship that would prevent them from functioning properly for five years from the date of purchase. This express warranty is extended by Cactus Technologies Limited

II. GENERAL PROVISIONS

This warranty sets forth the full extent of Cactus Technologies® responsibilities regarding the Cactus Technologies® Industrial Grade DOM products. In satisfaction of its obligations hereunder, Cactus Technologies®, at its sole option, will either repair, replace or refund the purchase price of the product.

NOTWITHSTANDING ANYTHING ELSE IN THIS LIMITED WARRANTY OR OTHERWISE, THE EXPRESS WARRANTIES AND OBLIGATIONS OF SELLER AS SET FORTH IN THIS LIMITED WARRANTY, ARE IN LIEU OF, AND BUYER EXPRESSLY WAIVES ALL OTHER OBLIGATIONS, GUARANTIES AND WARRANTIES OF ANY KIND, WHETHER EXPRESS OR IMPLIED, INCLUDING WITHOUT LIMITATION, ANY IMPLIED WARRANTY OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OR INFRINGEMENT, TOGETHER WITH ANY LIABILITY OF SELLER UNDER ANY CONTRACT, NEGLIGENCE, STRICT LIABILITY OR OTHER LEGAL OR EQUITABLE THEORY FOR LOSS OF USE, REVENUE, OR PROFIT OR OTHER INCIDENTAL OR CONSEQUENTIAL DAMAGES, INCLUDING WITHOUT LIMITATION PHYSICAL INJURY OR DEATH, PROPERTY DAMAGE, LOST DATA, OR COSTS OF PROCUREMENT OF SUBSTITUTE GOODS, TECHNOLOGY OR SERVICES. IN NO EVENT SHALL THE SELLER BE LIABLE FOR DAMAGES IN EXCESS OF THE PURCHASE PRICE OF THE PRODUCT, ARISING OUT OF THE USE OR INABILITY TO USE SUCH PRODUCT, TO THE FULL EXTENT SUCH MAY BE DISCLAIMED BY LAW.

Cactus Technologies® products are not warranted to operate without failure. Accordingly, in any use of products in life support systems or other applications where failure could cause injury or loss of life, the products should only be incorporated in systems designed with appropriate redundancy, fault tolerant or back-up features.

III. WHAT THIS WARRANTY COVERS

For products found to be defective within five years of purchase, Cactus Technologies® will have the option of repairing or replacing the defective product, if the following conditions are met:

A. The defective product is returned to Cactus Technologies® for failure analysis as soon as possible after the failure occurs.

B. An incident drive filled out by the user, explaining the conditions of usage and the nature of the failure, accompanies each returned defective product.

C. No evidence is found of abuse or operation of products not in accordance with the published specifications, or of exceeding storage or maximum ratings or operating conditions.

All failing products returned to Cactus Technologies® under the provisions of this limited warranty shall be tested to the product's functional and performance specifications. Upon confirmation of failure, each product will be analyzed, by whatever means necessary, to determine the root cause of failure. If the root cause of failure is found to be not covered by the above provisions, then the product will be returned to the customer with a report indicating why the failure was not covered under the warranty.

This warranty does not cover defects, malfunctions, performance failures or damages to the unit resulting from use in other than its normal and customary manner, misuse, accident or neglect; or improper alterations or repairs.

Cactus Technologies® reserves the right to repair or replace, at its discretion, any product returned by its customers, even if such product is not covered under warranty, but is under no obligation to do so.

Cactus Technologies® may, at its discretion, ship repaired or rebuilt products identified in the same way as new products, provided such drives meet or exceed the same published specifications as new products. Concurrently, Cactus Technologies® also reserves the right to market any products, whether new, repaired, or rebuilt, under different specifications and product designations if such products do not meet the original product's specifications.

IV. RECEIVING WARRANTY SERVICE

According to Cactus Technologies® warranty procedure, defective product should be returned only with prior authorization from Cactus Technologies Limited Please contact Cactus Technologies® Customer Service department with the following information: product model number and description, nature of defect, conditions of use, proof of purchase and purchase date. If approved, Cactus Technologies® will issue a Return Material Authorization or Product Repair Authorization number. Ship the defective product to:

Cactus Technologies Limited
Suite C, 15/F, Capital Trade Center
62 Tsun Yip Street, Kwun Tong
Kowloon, Hong Kong

Tel: +852-27972277
Fax: +852-27973777